

# The IMOCO4.E Team



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## KEY FACTS

Start: **1st September 2021**

Duration: **36 months**

Coordinator: **Arend-Jan Beltman**

Institution: **SIoux CCM B.V.**

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GA No.: **101007311 - H2020-ECSEL-2020**

Consortium: **45 Partners from 13 countries**

# iMOCO4.E

## Intelligent Motion Control under Industry4.E



The project has received funding from the Electronic Component Systems for European Leadership Joint Undertaking, under Grant Agreement n°101007311

# Pilots



**Pilot 1:** 3D printing  
**Lead:** Sioux, NL

**Pilot 2:** Semiconductor production  
**Lead:** ITEC B.V., NL



**Pilot 3:** High speed packaging  
**Lead:** CRIT, IT

**Pilot 4:** Healthcare robotics  
**Lead:** Philips Medical Systems, NL



**Pilot 5:** Mining/tunneling robotic boom Manipulator  
**Lead:** Normet, FI

# MISSION

**IMOCO4.E mission** is to provide distributed edge-to-cloud motion control intelligence for a wide range of Human-in-the-Loop Cyber-Physical Systems involving actively controlled moving elements.

**IMOCO4.E** will deliver a reference platform consisting of AI and digital twin toolchains and a set of mating building blocks for resilient manufacturing applications. The optimal energy efficient performance and easy configurability, traceability and cyber-security are crucial.

The **IMOCO4.E platform's benefits** will be directly verified in applications for **semiconductor, packaging, industrial robotics and healthcare**. While the project will demonstrate the results in other generic “motion-control-centred” domains affecting the entire value chain of the production automation and application markets.

# Demonstrators



**Demo 1:** Shaver blades  
**Lead:** Philips Consumer Lifestyle, NL

**Demo 2:** Plastic molding  
**Lead:** Edilásio, PT



**Demo 3:** Warehouse logistics  
**Lead:** Still, DE

**Demo 4:** Cosmetics production  
**Lead:** Madara Cosmetics, LV



# Use Cases



**Use case 1:** Industrial drive for smart mechatronics applications  
**Lead:** Gefran, IT

**Use case 2:** CNC for integrated machine tool and robot control  
**Lead:** Fagor Aotek & Tekniker, ES.



**Use case 3:** Tactile Robot Teleoperation  
**Lead:** Tyndall National Institute, IE

**Use case 4:** Advanced and Intuitive robot control and programming control  
**Lead:** University of West Bohemia, CZ



**IMOCO4.E** improves Industry 4.0 manufacturing productivity by:

- Combining and exploiting novel sensory information, model-based approaches and Industrial IoT philosophies to make **mechatronic systems smarter, more configurable, more reliable and faster** while simultaneously pushing their performance toward physical limits
- Assessing the demands placed on **future smart manufacturing** in Europe from a mechatronics and service-oriented point of view
- Establishing joint action of Industry 4.E and other relevant **Lighthouse projects** towards the identification and development of best practices and methods enhancing the European R&D ecosystem